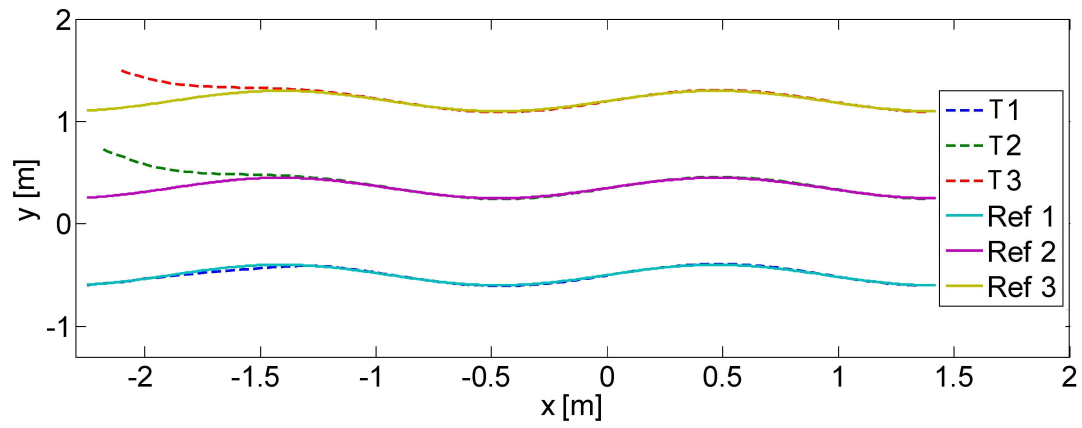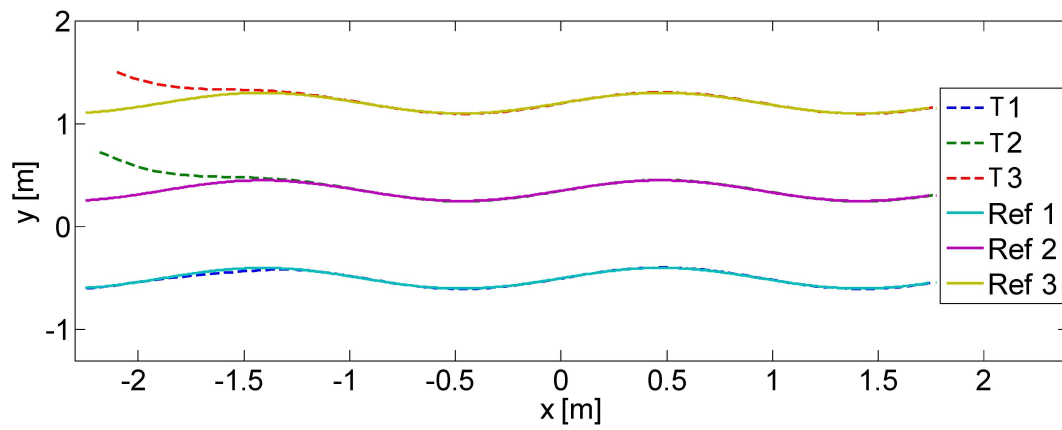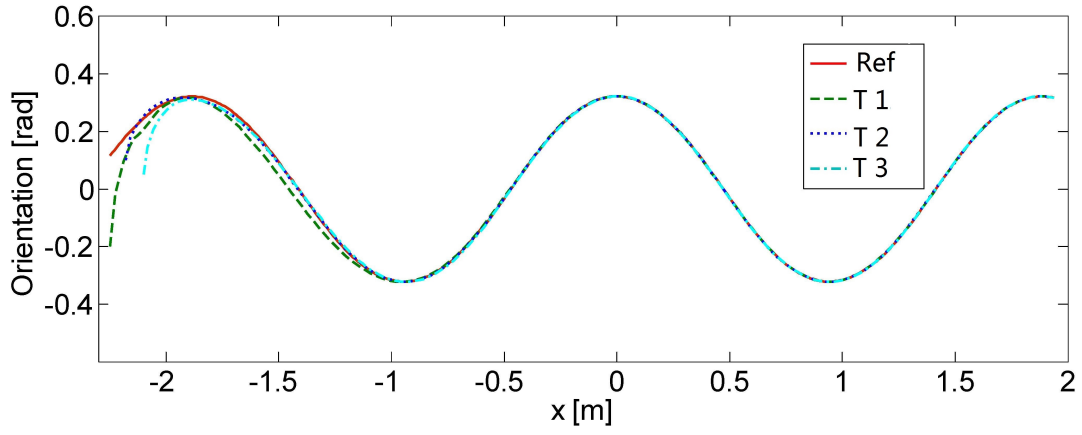(a) No time delays

(b) $c = 5T$ (without NPCC)

(c) $c = 5T$ (with NPCC)

Fig. 1. The trajectories of the hovercraft testbeds
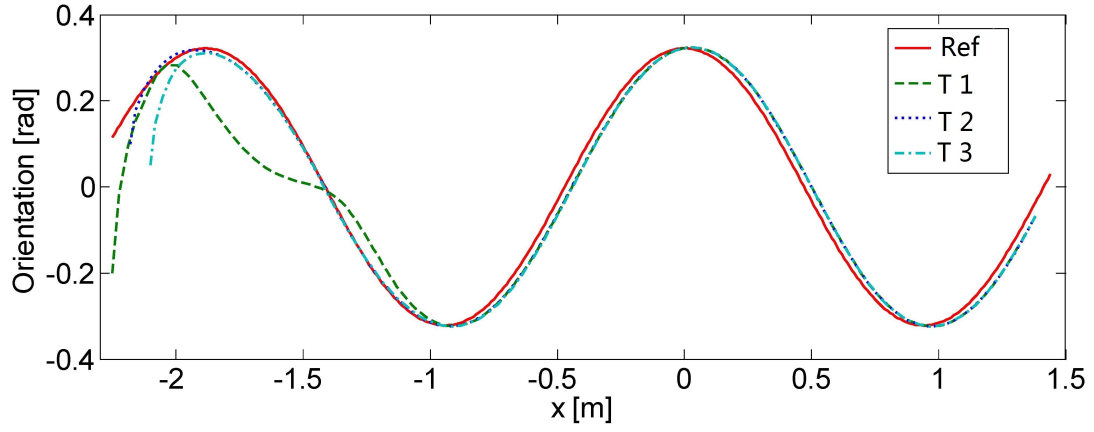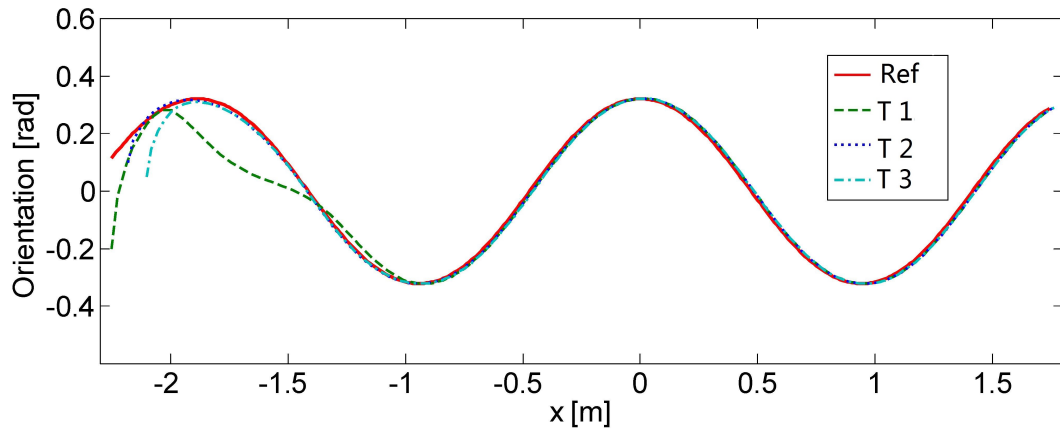
(a) No time delays

(b) $c = 5T$ (without NPCC)

(c) $c = 5T$ (with NPCC)

Fig. 2. The attitudes of the hovercraft testbeds