

Appendix A

Full System State Dependent Matrix Coefficients

$$\dot{x} = \begin{bmatrix} a_{11}(x) & \cdots & a_{115}(x) \\ \vdots & \ddots & \vdots \\ a_{151}(x) & \cdots & a_{1515}(x) \end{bmatrix} x + \begin{bmatrix} b_{11}(x) & \cdots & b_{14}(x) \\ \vdots & \ddots & \vdots \\ b_{151}(x) & \cdots & b_{154}(x) \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_{lon} \\ \theta_{lat} \\ \theta_{TR} \end{bmatrix}$$

where

$$x = [U_b \ V_b \ W_b \ p \ q \ r \ \phi \ \theta \ \psi \ \dot{\beta}_0 \ \dot{\beta}_{1c} \ \dot{\beta}_{1s} \ \beta_0 \ \beta_{1c} \ \beta_{1s}]^\top$$

$$\begin{aligned} a_{11}(x) = & -\frac{1}{M_{body}} \left[\left(\frac{c_3}{4} + \left(\frac{c_2}{8} \right) \beta_{1c}^2 + \left(\frac{c_4}{2} \right) |U_b| \right. \right. \\ & \left. \left. + \left(\frac{c_2}{16} e \right) \beta_{1s}^2 + \left(\frac{3c_2}{16} e \right) \beta_{1s}^2 \right] \right] \end{aligned}$$

$$a_{12}(x) = r + \frac{1}{M_{body}} \left[\left(\frac{c_2}{8} \right) \beta_{1s} \beta_{1c} \right], \quad a_{15}(x) = -W_b$$

$$a_{18}(x) = -g \frac{\sin(\theta)}{\theta}, \quad a_{113}(x) = -\frac{1}{M_{body}} \left[\left(\frac{c_1}{8} \right) e \right] \beta_{1s}$$

$$a_{114}(x) = \frac{\lambda_{MR}}{M_{body}} \left[\left(\frac{3c_1}{8} \right) - \left(\frac{5c_1}{8} \right) e^2 - \left(\frac{c_1}{4} \right) e \right] \beta_{1s}$$

$$\begin{aligned}
a_{115}(x) &= -\frac{1}{M_{body}} \left[\left(\frac{2c_1}{25} \right) \right] \beta_0 \\
a_{21}(x) &= -\frac{1}{M_{body}} \left(\frac{c_2}{8} \right) [\beta_{1s}\beta_{1c} + e\beta_{1s}\beta_{1c} - 6\lambda_{MR}\beta_0] \\
a_{22}(x) &= -\frac{1}{M_{body}} \left[\left(\frac{c_3}{8} \right) + \left(\frac{c_2}{8} \right) \beta_{1s}^2 + \left(\frac{c_8}{8} \right) |V_b| \right] \\
a_{24}(x) &= W_b, a_{26}(x) = -U_b, a_{27}(x) = -g \cos(\theta) \frac{\sin(\theta)}{\theta} \\
a_{214}(x) &= -\frac{1}{M_{body}} \left[\left(\frac{2c_1}{25} \right) \beta_0 \right] \\
a_{213}(x) &= \left[\frac{Cl_{TR}R_{TR}^3c_{CTR}\lambda_{TR}\Omega_{TR}^2\rho}{2M_{body}} \right] \frac{1}{\beta_0} \\
&\quad - \frac{1}{M_{body}} \left[\left(\frac{c_1}{8} \right) e \right] \beta_{1c} \\
a_{215}(x) &= \frac{\lambda_{MR}}{M_{body}} \left(\frac{c_1}{8} \right) [5e^2 - 3 - 2e] \beta_{1s} \\
a_{31}(x) &= \frac{1}{M_{body}} \left(\frac{c_2}{4} \right) e [e - 1] \beta_{1c} \\
a_{32}(x) &= \frac{1}{M_{body}} \left(\frac{c_2}{4} e \right) \beta_{1s} \\
a_{33}(x) &= -\frac{1}{M_{body}} \left(\frac{c_9}{2} \right) |V_b|, a_{34}(x) = -V_b, a_{35}(x) = U_b \\
a_{313}(x) &= \frac{1}{M_{body}} \left[\left(\frac{c_1}{4} \right) \lambda_{MR} \right] \frac{1}{\beta_0} + [g \cos(\phi) \cos(\theta)] \frac{1}{\beta_0} \\
&\quad + \frac{1}{M_{body}} \left[\left(\frac{c_1}{2} \right) e \lambda_{MR} \right] \frac{1}{\beta_0} - \frac{1}{M_{body}} \left[\left(\frac{3c_1}{4} \right) e^2 \lambda_{MR} \right] \frac{1}{\beta_0} \\
a_{41}(x) &= \frac{1}{I_{xx}} \left[\left(\frac{3c_2}{4} e R_{Z_{MR}} \lambda_{MR} \right) \beta_0 - \left(\frac{c_2}{4} e R_{Y_{MR}} \right) \beta_{1c} \right. \\
&\quad \left. + \left(\frac{c_2}{4} e^2 R_{Y_{MR}} \right) \beta_{1c} - \frac{c_2}{8} (R_{Z_{MR}} - e R_{Z_{MR}}) \beta_{1s} \beta_{1c} \right] \\
a_{42}(x) &= \frac{1}{I_{xx}} \left[\left(\frac{c_3}{4} + \frac{c_2}{8} \beta_{1s}^2 \right) R_{Z_{MR}} + \left(\frac{c_2}{4} e R_{Y_{MR}} \right) \beta_{1s} \right] \\
a_{45}(x) &= \frac{I_{yy}}{I_{xx}}(r) - \frac{I_{zz}}{I_{xx}}(r) \\
a_{413}(x) &= \frac{1}{I_{xx}} \left[\frac{c_1}{4} (1+e) R_{Y_{MR}} \lambda_{MR} - \left(\frac{3c_1}{4} e^2 R_{Y_{MR}} \lambda_{MR} \right) \right. \\
&\quad \left. - \left(\frac{(Cl_{TR}R_{TR}^3c_{CTR}\lambda_{TR}\Omega_{TR}^2\rho R_{Z_{TR}})}{2} \right) \right] \frac{1}{\beta_0} \\
a_{414}(x) &= \frac{1}{I_{xx}} \left[\left(\frac{2c_1}{25} R_{Z_{MR}} \right) \beta_0 + \left(\frac{c_1}{8} e R_{Z_{MR}} \right) \beta_0 \right] \\
a_{415}(x) &= \frac{1}{I_{xx}} \left[\left(\frac{3c_1}{8} R_{Z_{MR}} \lambda_{MR} \right) - \left(\frac{5c_1}{8} e^2 R_{Z_{MR}} \lambda_{MR} \right) \right. \\
&\quad \left. + \left(\frac{c_1}{4} e R_{Z_{MR}} \lambda_{MR} \right) \right] \\
a_{51}(x) &= \frac{1}{I_{yy}} \left[\left(\frac{c_2}{4} e R_{X_{MR}} \right) \beta_{1c} - \frac{c_3}{4} R_{Z_{MR}} - \left(\frac{c_2}{8} R_{Z_{MR}} \right) \beta_{1c}^2 \right. \\
&\quad \left. - \left(\frac{c_2}{16} e R_{Z_{MR}} \right) \beta_{1s}^2 - \left(\frac{c_2}{4} e^2 R_{X_{MR}} \right) \beta_{1c} - \left(\frac{3c_2}{16} e R_{Z_{MR}} \right) \beta_{1c}^2 \right] \\
a_{52}(x) &= \frac{1}{I_{yy}} \left[\left(\frac{c_2}{8} R_{Z_{MR}} \right) \beta_{1c} \beta_{1s} - \left(\frac{c_2}{4} e R_{X_{MR}} \right) \beta_{1s} \right] \\
a_{54}(x) &= -\frac{I_{xx}}{I_{yy}}(r), a_{56}(x) = \frac{I_{zz}}{I_{yy}}(p) \\
a_{513}(x) &= \frac{1}{I_{yy}} \left[\left(\frac{3c_1}{4} e^2 - \frac{c_1}{2} e - \frac{1}{4} \right) R_{X_{MR}} \lambda_{MR} \right] \frac{1}{\beta_0} \\
a_{514}(x) &= \frac{1}{I_{yy}} \left[\left(-\frac{5c_1}{8} e^2 + \frac{c_1}{4} e + \frac{3c_1}{8} \right) R_{Z_{MR}} \lambda_{MR} \right] \\
a_{515}(x) &= -\frac{1}{I_{yy}} \left[\left(\frac{c_1}{8} e + \frac{2c_1}{25} \right) R_{Z_{MR}} \beta_0 \right] \\
a_{61}(x) &= \frac{1}{I_{zz}} \left[\left(\frac{c_3}{4} R_{Y_{MR}} \right) + \left(\frac{3c_{12}}{32} U_b \right) \beta_{1c}^2 + \left(\frac{c_2}{8} R_{Y_{MR}} \right) \beta_{1c}^2 \right. \\
&\quad \left. - \left(\frac{c_{13}}{4} R_{Y_{MR}} \lambda_{MR} \right) \beta_{1c} - \left(\frac{3c_2}{4} R_{X_{MR}} \lambda_{MR} \right) \beta_0 + \left(\frac{c_2}{16} e R_{Y_{MR}} \right) \right. \\
&\quad \beta_{1s}^2 + \left(\frac{3c_2}{16} e R_{Y_{MR}} \right) \beta_{1c}^2 + \left(\frac{3c_2}{16} e R_{Y_{MR}} \right) + \left(\frac{4c_{13}}{25} \right) \beta_0 \beta_{1s} \\
&\quad + \left(\frac{c_2}{8} R_{X_{MR}} \right) \beta_{1s} \beta_{1c} + \left(\frac{c_2}{8} e R_{X_{MR}} \right) \beta_{1s} \beta_{1c} - \left(\frac{c_{13}}{2} e \lambda_{MR} \right) \beta_{1c} \left. \right] \\
a_{62}(x) &= \frac{1}{I_{zz}} \left[\left(\frac{c_{13}}{4} \lambda_{MR} \right) \beta_{1s} - \left(\frac{c_3}{4} - \frac{c_2}{8} \beta_{1s}^2 \right) R_{X_{MR}} \right. \\
&\quad \left. - \left(\frac{c_2}{8} R_{Y_{MR}} \right) \beta_{1s} \beta_{1c} \right] \\
a_{64}(x) &= -\frac{I_{yy}}{I_{zz}}(q), a_{65}(x) = \frac{I_{xx}}{I_{zz}}(p) \\
a_{613}(x) &= \frac{1}{I_{zz}\beta_0} \left[\left(\frac{c_{10}}{4} \lambda_{MR}^2 \right) - \left(\frac{c_{11}}{8} \right) + \left(\frac{c_{10}}{2} e \lambda_{MR}^2 \right) \right. \\
&\quad \left. - \left(\frac{c_{11}}{2} e \right) + \left(\frac{Cl_{TR}R_{TR}^3c_{CTR}\lambda_{TR}\Omega_{TR}^2\rho R_{X_{TR}}}{2} \right) \right] \\
a_{614}(x) &= \frac{1}{I_{zz}} \left[\left(\frac{c_{10}}{16} \right) \beta_{1c} - \left(\frac{2c_1}{25} R_{X_{MR}} \right) \beta_0 + \left(\frac{2c_{10}}{25} e \right) \beta_{1c} \right. \\
&\quad \left. - \left(\frac{3c_1}{8} \lambda_{MR} R_{Y_{MR}} \right) + \left(\frac{5c_1}{8} e^2 \lambda_{MR} R_{Y_{MR}} \right) \right. \\
&\quad \left. - \left(\frac{c_1}{8} e R_{X_{MR}} \right) \beta_0 - \left(\frac{c_1}{4} e R_{Y_{MR}} \lambda_{MR} \right) \right] \\
a_{615}(x) &= \frac{1}{I_{zz}} \left[\left(\frac{c_{10}}{16} \right) \beta_{1s} - \left(\frac{2c_1}{25} R_{Y_{MR}} \right) \beta_0 + \left(\frac{2c_{10}}{25} e \right) \beta_{1s} \right. \\
&\quad \left. - \left(\frac{3c_1}{8} \lambda_{MR} R_{X_{MR}} \right) + \left(\frac{5c_1}{8} e^2 \lambda_{MR} R_{X_{MR}} \right) \right. \\
&\quad \left. + \left(\frac{c_1}{8} e R_{Y_{MR}} \right) \beta_0 - \left(\frac{c_1}{4} e R_{X_{MR}} \lambda_{MR} \right) \right] \\
a_{36}(x) &= a_{37}(x) = a_{38}(x) = a_{39}(x) = a_{310}(x) = a_{311}(x) \\
&= a_{312}(x) = a_{314}(x) = a_{315}(x) = 0
\end{aligned}$$

$$\begin{aligned} a_{13}(x) &= a_{14}(x) = a_{16}(x) = a_{17}(x) = a_{19}(x) = a_{110}(x) \\ &= a_{111}(x) = a_{112}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{23}(x) &= a_{25}(x) = a_{28}(x) = a_{29}(x) = a_{210}(x) = a_{211}(x) \\ &= a_{212}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{43}(x) &= a_{44}(x) = a_{46}(x) = a_{47}(x) = a_{48}(x) = a_{49}(x) \\ &= a_{410}(x) = a_{411}(x) = a_{412}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{53}(x) &= a_{55}(x) = a_{57}(x) = a_{58}(x) = a_{59}(x) = a_{510}(x) \\ &= a_{511}(x) = a_{512}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{63}(x) &= a_{66}(x) = a_{67}(x) = a_{68}(x) = a_{69}(x) = a_{610}(x) \\ &= a_{611}(x) = a_{612}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{71}(x) &= a_{72}(x) = a_{73}(x) = a_{77}(x) = a_{78}(x) = a_{79}(x) \\ &= a_{710}(x) = a_{711}(x) = a_{712}(x) = a_{713}(x) = a_{714}(x) \\ &= a_{715}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{81}(x) &= a_{82}(x) = a_{83}(x) = a_{84}(x) = a_{87}(x) = a_{88}(x) \\ &= a_{89}(x) = a_{810}(x) = a_{811}(x) = a_{812}(x) = a_{813}(x) \\ &= a_{814}(x) = a_{815}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{91}(x) &= a_{92}(x) = a_{93}(x) = a_{94}(x) = a_{97}(x) = a_{98}(x) \\ &= a_{99}(x) = a_{910}(x) = a_{911}(x) = a_{912}(x) = a_{913}(x) \\ &= a_{914}(x) = a_{915}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{103}(x) &= a_{104}(x) = a_{105}(x) = a_{106}(x) = a_{107}(x) = a_{108}(x) \\ &= a_{109}(x) = a_{1014}(x) = a_{1015}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{113}(x) &= a_{114}(x) = a_{115}(x) = a_{116}(x) = a_{117}(x) = a_{118}(x) \\ &= a_{119}(x) = a_{1110}(x) = a_{1113}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{123}(x) &= a_{124}(x) = a_{125}(x) = a_{126}(x) = a_{127}(x) = a_{128}(x) \\ &= a_{129}(x) = a_{1210}(x) = a_{1213}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{131}(x) &= a_{132}(x) = a_{133}(x) = a_{134}(x) = a_{135}(x) = a_{136}(x) \\ &= a_{137}(x) = a_{138}(x) = a_{139}(x) = a_{1311}(x) = a_{1312}(x) \\ &= a_{1313}(x) = a_{1314}(x) = a_{1315}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{141}(x) &= a_{142}(x) = a_{143}(x) = a_{144}(x) = a_{145}(x) = a_{146}(x) \\ &= a_{147}(x) = a_{148}(x) = a_{149}(x) = a_{1310}(x) = a_{1412}(x) \\ &= a_{1413}(x) = a_{1414}(x) = a_{1415}(x) = 0 \end{aligned}$$

$$\begin{aligned} a_{151}(x) &= a_{152}(x) = a_{153}(x) = a_{154}(x) = a_{155}(x) = a_{156}(x) \\ &= a_{157}(x) = a_{158}(x) = a_{159}(x) = a_{1510}(x) = a_{1511}(x) \\ &= a_{1513}(x) = a_{1514}(x) = a_{1515}(x) = 0 \end{aligned}$$

$$a_{75} = \sin(\psi) \tan(\theta), a_{76}(x) = \cos(\psi) \tan(\theta), a_{85}(x) = \cos(\psi)$$

$$a_{86}(x) = \sin(\psi), a_{95}(x) = \frac{\sin(\psi)}{\cos(\theta)}, a_{96}(x) = \frac{\cos(\phi)}{\cos(\theta)}$$

$$a_{101}(x) = \left(\frac{e\gamma_{MR}\Omega_{MR}}{8R_{MR}} \right) \beta_{1c}, a_{102}(x) = -\left(\frac{e\gamma_{MR}\Omega_{MR}}{8R_{MR}} \right) \beta_{1s}$$

$$a_{1010}(x) = -\left(\frac{\gamma_{MR}\Omega_{MR}}{8} + \frac{416e\gamma_{MR}\Omega_{MR}}{2497} \right)$$

$$a_{1011}(x) = -\left(\frac{208\gamma_{MR}}{2497R_{MR}} \right) V_b, a_{1012}(x) = -\left(\frac{208\gamma_{MR}}{2497R_{MR}} \right) U_b$$

$$\begin{aligned} a_{1013}(x) &= -K_s - \Omega_{MR}^2 - \left(\frac{416\gamma\lambda_{MR}\Omega_{MR}^2}{2497} \right) \frac{1}{\beta_{1c}} \\ &\quad - \left(\frac{e\gamma\lambda_{MR}\Omega_{MR}^2}{4} \right) \frac{1}{\beta_0} \end{aligned}$$

$$\begin{aligned} a_{111}(x) &= \frac{\gamma_{MR}\Omega_{MR}}{R} \left[\left(\frac{416}{2497} + \frac{e}{4} \right) \beta_0 \right] + \frac{\gamma_{MR}}{R_{MR}^2} \left[\left(\frac{1}{16} \right) U_b \beta_{1s} \right. \\ &\quad \left. + \left(\frac{1}{8} \right) V_b \beta_{1c} \right] \end{aligned}$$

$$a_{112}(x) = -\frac{416\gamma_{MR}}{2497} \beta_0 + \frac{\gamma_{MR}}{16R_{MR}^2} V_b \beta_{1s} - \frac{\gamma_{MR}\lambda_{MR}\Omega_{MR}}{4R_{MR}}$$

$$a_{1111}(x) = -\frac{\lambda_{MR}\Omega_{MR}}{8} \left(1 + \frac{e}{2} \right), a_{1112}(x) = 2\Omega_{MR}$$

$$a_{1114}(x) = -K_s, a_{1115}(x) = \frac{\lambda_{MR}\Omega_{MR}}{8} \left(1 + \frac{e}{2} \right)$$

$$a_{121}(x) = \frac{\lambda_{MR}}{R_{MR}} \left[\frac{\lambda_{MR}\Omega_{MR}}{4} - \frac{1}{16} \dot{\beta}_0 \right] + \frac{\lambda_{MR}}{R_{MR}^2} \left[\frac{416}{2497} U_b \beta_{1c} \right]$$

$$\begin{aligned} a_{122}(x) &= \frac{\lambda_{MR}}{R_{MR}^2} \left[\left(\frac{1}{8} \right) U_b \beta_{1c} - \left(\frac{416}{2497} + \right) V_b \beta_{1c} \right] \\ &\quad + \frac{\lambda_{MR}\Omega_{MR}}{R_{MR}} \left[- \left(\frac{\Omega_{MR}}{16} + \frac{e}{4} \right) \beta_0 \right] \end{aligned}$$

$$a_{1211}(x) = -2\Omega_{MR}, a_{1212}(x) = -\frac{\lambda_{MR}\Omega_{MR}}{8} \left(1 + \frac{e}{2} \right)$$

$$a_{1214}(x) = -\frac{\lambda_{MR}\Omega_{MR}^2}{8} \left(1 + \frac{e}{2} \right), a_{1215}(x) = -K_s$$

$$a_{74}(x) = a_{1310}(x) = a_{1411}(x) = a_{1512}(x) = 1$$

$B(x)$ state dependent coefficient matrix

$$b_{11}(x) = -\frac{c_1}{M_{body}} \left[\left(\frac{1}{16} + \frac{3e}{8} + \frac{e^2}{4} \right) \beta_{1c} \right] - \frac{c_2\lambda_{MR}}{4M_{body}} U_b$$

$$b_{13}(x) = -\frac{c_1}{M_{body}} \left[\left(\frac{208}{2497} + \frac{e}{4} \right) \beta_0 \right] - \left(\frac{c_2}{4M_{body}} \right) V_b \beta_{1c}$$

$$\begin{aligned} b_{12}(x) &= \frac{c_1}{M_{body}} \left[\frac{\lambda_{MR}}{8} + \frac{e\lambda_{MR}}{4} - \frac{e^2\lambda_{MR}}{8} \right] + \frac{c_2}{16M_{body}} [2U_b \beta_{1c} \\ &\quad + 2V_b \beta_{1s} + eU_b \beta_{1c}] \end{aligned}$$

$$\begin{aligned} b_{21}(x) &= \frac{c_1}{M_{body}} \left[\left(\frac{e^2}{4} \right) \beta_{1s} + \left(\frac{e}{8} + \frac{416}{2497} \right) \beta_{1s} \right] + \frac{c_7 U_b^2 \beta_{1s}}{4M_{body}} \\ &\quad + \frac{c_2}{M_{body}} \left[\left(\frac{3e^2}{8} \right) U_b \beta_0 - \left(\frac{\lambda_{MR}}{4} \right) V_b \right] \end{aligned}$$

$$b_{22}(x) = -\frac{c_1}{M_{body}} \left[\left(\frac{e}{4} + \frac{208}{2497} \right) \beta_0 \right] + \frac{c_2}{M_{body}} \left[\left(\frac{11e^2}{16} + \frac{1}{4} - \frac{7e}{16} \right) U_b \beta_{1s} \right]$$

$$b_{23}(x) = \frac{c_1}{M_{body}} \left[\frac{\lambda_{MR}}{8} (1 - 2e + 3e^2) \right] + \frac{c_2}{M_{body}} \left[\frac{1}{8} V_b \beta_{1s} + \left(\frac{1}{8} + \frac{5e}{16} \right) U_b \beta_{1c} \right]$$

$$b_{24}(x) = - \left[\frac{Cl_{TR} R_{TR} c_{TR} \rho}{2M_{body}} \right] U_b^2 - \left[\frac{Cl_{TR} R_{TR} c_{TR} \rho}{2M_{body}} \right] W_b^2 - \frac{33}{100} \left[\frac{Cl_{TR} R_{TR}^3 c_{TR} \Omega_{TR}^2 \rho}{M_{body}} \right]$$

$$b_{31}(x) = -\frac{c_1}{M_{body}} \left(\frac{4}{25} + \frac{1}{2}e + \frac{1}{2}e^2 - \frac{29}{25}e^3 \right) - \frac{c_7}{4M_{body}} U_b^2$$

$$b_{32}(x) = \frac{c_2 U_b}{M_{body}} \left(\frac{1}{4} + \frac{e}{2} - \frac{3e^2}{4} \right), b_{33}(x) = -\frac{c_2 V_b}{M_{body}} \left(\frac{1}{4} + \frac{e}{2} \right)$$

$$b_{41}(x) = \frac{c_1}{I_{xx}} \left\{ \left(-\frac{4}{25} - \frac{e}{2} - \frac{e^2}{2} + \frac{29e^3}{25} \right) R_{Y_{MR}} - \left[\left(\frac{e^2}{4} + \frac{3e}{8} + \frac{4}{25} \right) R_{Z_{MR}} \right] \beta_{1s} \right\} + \frac{c_2}{I_{xx}} \left\{ R_{Z_{MR}} \left[\left(-\frac{3}{8} \right) U_b \beta_0 + (\lambda_{MR} 4) V_b \right] - \frac{c_7}{4I_{xx}} \{ (R_{Z_{MR}}) U_b^2 \beta_{1s} + (R_{Y_{MR}}) U_b^2 \} \right\}$$

$$b_{42}(x) = \frac{c_1}{I_{xx}} \left\{ \left(-\frac{e}{2} - \frac{e^2}{2} + \frac{29e^3}{25} R_{Y_{MR}} \right) + \left[\left(\frac{e}{4} + \frac{208}{2497} R_{Z_{MR}} \right) \beta_0 \right] + \frac{c_2}{I_{xx}} \left\{ R_{Z_{MR}} \left[\left(\frac{11e^2}{16} + \frac{7e}{16} + \frac{1}{4} \right) U_b \beta_{1s} + R_{Y_{MR}} \left[\left(-\frac{3e^2}{4} + \frac{e}{2} + \frac{1}{4} \right) U_b \right] \right\} \right\}$$

$$b_{43}(x) = \frac{c_1}{I_{xx}} \left[\frac{\lambda_{MR}}{8} (1 + 2e - 3e^2) R_{Z_{MR}} \right] - \frac{c_2}{I_{xx}} \{ R_{Z_{MR}} \left[\left(\left(\frac{5e}{16} \right) U_b \beta_{1c} + \left(\frac{1}{8} \right) V_b \beta_{1s} + \left(\frac{1}{8} \right) U_b \beta_0 \right) \right] + R_{Y_{MR}} \left[\left(\frac{e}{2} + \frac{1}{4} \right) V_b \right] \}$$

$$b_{44}(x) = \frac{33}{100} \left[\frac{Cl_{TR} R_{TR}^3 c_{TR} \omega_{TR}^2 \rho}{I_{xx}} R_{Z_{TR}} \right] + \left[\frac{Cl_{TR} R_{TR} c_{TR} \rho}{2I_{xx}} R_{Z_{TR}} \right] U_b^2 + \left[\frac{Cl_{TR} R_{TR} c_{TR} \rho}{2I_{xx}} R_{Z_{TR}} \right] W_b^2$$

$$b_{51}(x) = \frac{c_1}{I_{yy}} \left\{ \left(\frac{4}{25} + \frac{e}{2} + \frac{e^2}{2} + \frac{29e^3}{25} \right) R_{X_{MR}} - \left[\left(\frac{e^2}{4} + \frac{3e}{8} + \frac{4}{25} \right) R_{Z_{MR}} \right] \beta_{1c} \right\} + \frac{c_7}{4I_{yy}} [(R_{X_{MR}}) U_b^2]$$

$$b_{52}(x) = \frac{1}{I_{yy}} \left[\left(\frac{c_1}{8} R_{Z_{MR}} \lambda_{MR} \right) - \left(\frac{c_2}{4} R_{X_{MR}} \right) U_b + \left(\frac{3c_2}{4} R_{X_{MR}} e^2 \right) U_b + \left(\frac{c_1}{4} R_{Z_{MR}} e \lambda_{MR} \right) + \left(\frac{c_2}{8} R_{Z_{MR}} \right) U_b \beta_{1c} + \left(\frac{c_2}{8} R_{Z_{MR}} \right) V_b \beta_{1s} - \left(\frac{c_2}{2} e R_{X_{MR}} \right) U_b - \left(\frac{3c_1}{8} R_{Z_{MR}} e^2 \lambda_{MR} \right) + \left(\frac{c_2}{16} R_{Z_{MR}} e \right) U_b \beta_{1c} \right]$$

$$b_{53}(x) = \frac{1}{I_{yy}} \left[\left(\frac{c_2}{4} R_{X_{MR}} \right) V_b - \left(\frac{2c_1}{25} - \frac{c_1}{4} e \right) R_{Z_{MR}} \beta_0 - \left(\frac{c_2}{4} R_{Z_{MR}} \right) V_b \beta_{1c} + \left(\frac{c_2}{2} e R_{X_{MR}} \right) V_b \right]$$

$$b_{61}(x) = \frac{1}{I_{zz}} \left[\left(\frac{4c_1}{25} R_{X_{MR}} \right) \beta_{1s} + \left(\frac{4c_1}{25} R_{Y_{MR}} \right) \beta_{1c} - \left(\frac{4c_{10}}{25} \lambda_{MR} \right) + \left(\frac{3c_1}{8} e R_{X_{MR}} \right) \beta_{1s} + \left(\frac{3c_1}{8} e R_{Y_{MR}} \right) \beta_{1c} - \left(\frac{c_{10}}{2} e \lambda_{MR} \right) + \left(\frac{3c_2}{8} R_{X_{MR}} \right) U_b \beta_0 + \left(\frac{c_2}{4} R_{Y_{MR}} \lambda_{MR} \right) U_b - \left(\frac{c_2}{4} R_{X_{MR}} \lambda_{MR} \right) V_b + \left(\frac{c_1}{4} R_{X_{MR}} e^2 \right) \beta_{1s} + \left(\frac{c_1}{4} R_{Y_{MR}} e^2 \right) \beta_{1c} + \left(\frac{c_7}{4} R_{X_{MR}} \right) \beta_{1s} U_b^2 + \left(\frac{c_1}{8} e \right) \beta_{1c} U_b \right]$$

$$b_{62}(x) = \frac{1}{I_{zz}} \left[\left(\frac{c_{10}}{16} \right) \beta_{1c} - \left(\frac{2c_1}{25} R_{X_{MR}} \right) \beta_0 - \left(\frac{c_1}{8} R_{Y_{MR}} \lambda_{MR} \right) + \left(\frac{4c_{10}}{25} e \right) \beta_{1c} - \left(\frac{c_1}{4} R_{X_{MR}} e \right) \beta_0 - \left(\frac{c_1}{4} R_{Y_{MR}} e \lambda_{MR} \right) - \left(\frac{c_2}{4} R_{X_{MR}} \right) U_b \beta_{1s} - \left(\frac{c_2}{8} R_{Y_{MR}} \right) U_b \beta_{1c} - \left(\frac{c_2}{8} R_{Y_{MR}} \right) V_b \beta_{1s} + \left(\frac{c_1}{8} \lambda_{MR} \right) U_b + \left(\frac{c_1}{8} e^2 \right) \beta_{1c} + \left(\frac{3c_1}{8} R_{Y_{MR}} e^2 \lambda_{MR} \right) - \left(\frac{c_{12}}{32} \right) \beta_{1c} U_b^2 - \left(\frac{7c_2}{16} R_{X_{MR}} e \right) U_b \beta_{1s} - \left(\frac{c_2}{16} R_{Y_{MR}} e \right) \beta_{1c} U_b + \left(\frac{c_{13}}{4} e \lambda_{MR} \right) U_b + \left(\frac{11c_2}{16} R_{X_{MR}} e^2 \right) \beta_{1s} U_b \right]$$

$$b_{63}(x) = \frac{1}{I_{zz}} \left[\left(\frac{c_{10}}{16} \right) \beta_{1s} + \left(\frac{2c_1}{25} R_{Y_{MR}} \right) \beta_0 - \left(\frac{c_1}{8} R_{X_{MR}} \lambda_{MR} \right) + \left(\frac{4c_{10}}{25} e \right) \beta_{1s} + \left(\frac{c_1}{4} R_{Y_{MR}} e \right) \beta_0 - \left(\frac{c_1}{4} R_{X_{MR}} e \lambda_{MR} \right) + \left(\frac{c_2}{8} R_{X_{MR}} \right) U_b \beta_{1c} + \left(\frac{c_2}{8} R_{X_{MR}} \right) V_b \beta_{1s} + \left(\frac{c_2}{4} R_{Y_{MR}} \right) V_b \beta_{1c} + \left(\frac{c_{10}}{8} e^2 \right) \beta_{1s} + \left(\frac{3c_1}{8} R_{X_{MR}} e^2 \lambda_{MR} \right) + \left(\frac{5c_2}{16} R_{X_{MR}} e \right) \beta_{1c} U_b \right]$$

$$b_{64}(x) = -\frac{Cl_{TR} R_{TR} R_{X_{TR}} c_{TR} \rho}{2I_{zz}} \left(U_b^2 + W_b^2 + \frac{3R_{TR}^2 \Omega_{TR}^2}{5} \right)$$

$$b_{101}(x) = \left[\frac{\gamma_{MR} \Omega_{MR}^2}{8} + \frac{\gamma_{MR}}{8R_{MR}^2} (U_b^2 + V_b^2) + \frac{3}{10} e \gamma_{MR} \Omega_{MR}^2 \right]$$

$$b_{102}(x) = - \left(\frac{4\gamma_{MR} \Omega_{MR}}{25R_{MR}} + \frac{e\gamma_{MR} \Omega_{MR}}{4R} \right) U_b$$

$$b_{103}(x) = \left(\frac{4\gamma_{MR} \Omega_{MR}}{25R_{MR}} + \frac{e\gamma_{MR} \Omega_{MR}}{4R_{MR}} \right) V_b$$

$$b_{111}(x) = \left(\frac{3\gamma_{MR} \Omega_{MR}}{10R} + \frac{e\gamma_{MR} \Omega_{MR}}{2R} \right) V_b$$

$$b_{112}(x) = - \left(\frac{\gamma_{MR}}{8R_{MR}^2} \right) U_b V_b$$

$$b_{113}(x) = \left[\frac{\gamma_{MR} \Omega_{MR}^2}{8} + \left(\frac{\gamma_{MR}}{16R_{MR}^2} \right) U_b^2 + \left(\frac{3\gamma_{MR}}{16R_{MR}^2} \right) V_b^2 + \frac{3}{10} e \gamma_{MR} \Omega_{MR}^2 \right]$$

$$b_{121}(x) = \left(\frac{3\gamma_{MR}\Omega_{MR}}{10R_{MR}} + \frac{e\gamma_{MR}\Omega_{MR}}{2R_{MR}} \right) U_b$$

$$b_{122}(x) = \left[\frac{\gamma_{MR}\Omega_{MR}^2}{8} + \left(\frac{3\gamma_{MR}}{16R_{MR}^2} \right) U_b^2 + \left(\frac{\gamma_{MR}}{16R_{MR}^2} \right) V_b^2 \right. \\ \left. + \frac{3}{10}e\gamma_{MR}\Omega_{MR}^2 \right]$$

$$b_{123}(x) = \left(\frac{\gamma_{MR}}{8R_{MR}^2} \right) U_b V_b$$

$$\begin{aligned} b_{34}(x) &= b_{14}(x) = b_{54}(x) = b_{71}(x) = b_{72}(x) = b_{73}(x) \\ &= b_{74}(x) = b_{81}(x) = b_{82}(x) = b_{83}(x) = b_{84}(x) \\ &= b_{91}(x) = b_{92}(x) = b_{93}(x) = b_{94}(x) = b_{104}(x) \\ &= b_{114}(x) = b_{124}(x) = b_{131}(x) = b_{132}(x) = b_{133}(x) \\ &= b_{134}(x) = b_{141}(x) = b_{142}(x) = b_{143}(x) = b_{144}(x) \\ &= b_{151}(x) = b_{152}(x) = b_{153}(x) = b_{154}(x) = 0 \end{aligned}$$

SAS Loop State Dependent Matrix Coefficients

$$\begin{aligned} a_{11}(x_{SAS}) &= a_{22}(x_{SAS}) = a_{33}(x_{SAS}) = a_{14}(x_{SAS}) \\ &= a_{15}(x_{SAS}) = a_{16}(x_{SAS}) = a_{24}(x_{SAS}) \\ &= a_{25}(x_{SAS}) = a_{26}(x_{SAS}) = a_{34}(x_{SAS}) \\ &= a_{35}(x_{SAS}) = a_{42}(x_{SAS}) = a_{43}(x_{SAS}) \\ &= a_{44}(x_{SAS}) = a_{45}(x_{SAS}) = a_{46}(x_{SAS}) = 0 \end{aligned}$$

$$\begin{aligned} a_{51}(x_{SAS}) &= a_{53}(x_{SAS}) = a_{54}(x_{SAS}) = a_{55}(x_{SAS}) \\ &= a_{56}(x_{SAS}) = a_{61}(x_{SAS}) = a_{62}(x_{SAS}) \\ &= a_{64}(x_{SAS}) = a_{65}(x_{SAS}) = a_{66}(x_{SAS}) = 0 \end{aligned}$$

$$a_{41}(x_{SAS}) = a_{52}(x_{SAS}) = a_{63}(x_{SAS}) = 1$$

$$a_{12}(x_{SAS}) = \left(\frac{I_{yy}}{I_{xx}} \right) r, a_{13}(x_{SAS}) = - \left(\frac{I_{zz}}{I_{xx}} \right) q$$

$$a_{21}(x_{SAS}) = - \left(\frac{I_{xx}}{I_{yy}} \right) r, a_{23}(x_{SAS}) = \left(\frac{I_{zz}}{I_{yy}} \right) p$$

$$a_{31}(x_{SAS}) = \frac{I_{xx}}{I_{yy}}, a_{32}(x_{SAS}) = - \left(\frac{I_{yy}}{I_{zz}} \right) p$$

$$b_{11}(x) = \frac{c_1}{I_{xx}} \left\{ \left[\left(\frac{2}{25} + \frac{e}{4} \right) R_{Z_{MR}} \right] \beta_0 \right\} + \frac{c_2}{I_{xx}} \left\{ \left[\left(\frac{1}{4} + \frac{e}{2} \right. \right. \right. \\ \left. \left. \left. - \frac{3e^2}{4} \right) R_{Y_{MR}} \right] U_b + \left[\left(\frac{1}{4} + \frac{7e}{16} - \frac{11e^2}{16} \right) R_{Z_{MR}} \right] \beta_{1s} U_b \right\}$$

$$b_{12}(x) = \frac{c_1}{I_{xx}} \left\{ \left[\left(\frac{1}{8} + \frac{e}{4} - \frac{3e^2}{8} \right) \lambda_{MR} R_{Z_{MR}} \right] \right\} - \frac{c_2}{I_{xx}} \left\{ \left[\left(\frac{1}{4} \right. \right. \\ \left. \left. + \frac{e}{2} \right) R_{Y_{MR}} \right] V_b + \left[\left(\frac{1}{8} + \frac{5e}{16} \right) R_{Z_{MR}} \right] \beta_{1c} U_b + \left[\left(\frac{1}{8} \right. \right. \\ \left. \left. R_{Z_{MR}} \right] \beta_{1s} V_b \right\}$$

$$b_{13}(x) = \frac{Cl_{TR}R_{TR}c_{TR}\rho R_{Z_{TR}}}{I_{xx}} \left(\frac{33R_{TR}^2\Omega_{TR}^2}{100} + \frac{U_b^2}{2} + \frac{W_b^2}{2} \right)$$

$$b_{21}(x) = \frac{c_1}{I_{yy}} \left\{ \left[\left(\frac{1}{8} + \frac{e}{4} - \frac{3e^2}{8} \right) \lambda_{MR} R_{Z_{MR}} \right] \right\} - \frac{c_2}{I_{yy}} \left\{ \left[\left(\frac{1}{4} \right. \right. \\ \left. \left. + \frac{e}{2} - \frac{3e^2}{4} \right) R_{X_{MR}} \right] U_b + \left[\left(-\frac{1}{8} - \frac{e}{16} \right) R_{Z_{MR}} \right] \beta_{1c} U_b \\ + \left[\left(-\frac{1}{8} \right) R_{Z_{MR}} \right] \beta_{1s} V_b \right\}$$

$$b_{22}(x) = - \frac{c_1}{I_{yy}} \left\{ \left[\left(\frac{2}{25} + \frac{e}{4} \right) R_{Z_{MR}} \right] \beta_0 \right\} + \frac{c_2}{I_{yy}} \left\{ \left[\left(\frac{1}{4} + \frac{e}{2} \right) \right. \\ \left. R_{X_{MR}} \right] V_b - \left[\left(\frac{1}{4} \right) R_{Z_{MR}} \right] \beta_{1c} V_b \right\}$$

$$b_{23} = 0$$

$$b_{31}(x) = \frac{c_1}{I_{zz}} \left\{ \left[\left(\frac{1}{16} + \frac{4e}{25} + \frac{e^2}{8} \right) R_{MR} \right] \beta_{1c} - \left[\left(\frac{2}{25} + \frac{e}{4} \right) \right. \right. \\ \left. \left. R_{X_{MR}} \right] \beta_0 - \left[\left(\frac{1}{8} + \frac{e}{4} - \frac{3e^2}{8} \right) \lambda_{MR} R_{Y_{MR}} \right] \right\} - \frac{c_2}{I_{zz}} \\ \left\{ \left[\left(\frac{1}{4} + \frac{7e}{16} - \frac{11e^2}{16} \right) R_{X_{MR}} \right] \beta_{1s} U_b + \left[\left(\frac{1}{8} - \frac{e}{16} \right) \right. \right. \\ \left. \left. R_{Y_{MR}} \right] \beta_{1c} U_b + \left[\left(\frac{1}{8} \right) R_{Y_{MR}} \right] \beta_{1s} V_b + \left[\left(-\frac{1}{8} + \frac{e}{4} \right) \right. \right. \\ \left. \left. R_{MR} \lambda_{MR} \right] U_b \right\} - \left(\frac{c_7}{32I_{zz}} R_{MR} \right) \beta_{1c} U_b^2$$

$$b_{32}(x) = \frac{c_1}{I_{zz}} \left\{ \left[\left(\frac{1}{16} + \frac{4e}{25} + \frac{e^2}{8} \right) R_{MR} \right] \beta_{1s} - \left[\left(\frac{1}{8} + \frac{e}{4} \right. \right. \right. \\ \left. \left. + \frac{3e^2}{8} \right) \lambda_{MR} R_{X_{MR}} \right] + \left[\left(\frac{2}{25} + \frac{e}{4} - \frac{3e^2}{8} \right) R_{Y_{MR}} \right] \beta_0 \right\} \\ + \frac{c_2}{I_{zz}} \left\{ \left[\left(\frac{1}{8} + \frac{5e}{16} \right) R_{X_{MR}} \right] \beta_{1c} U_b + \left[\left(\frac{1}{8} \right) R_{X_{MR}} \right] \right. \\ \left. \beta_{1s} V_b + \left[\left(\frac{1}{4} - \frac{e}{16} \right) R_{Y_{MR}} \right] \beta_{1c} V_b \right\}$$

$$b_{33}(x) = \frac{Cl_{TR}R_{TR}c_{TR}\rho R_{Z_{TR}}}{I_{zz}} \left(-\frac{33R_{TR}^2\Omega_{TR}^2}{100} + \frac{U_b^2}{2} + \frac{W_b^2}{2} \right)$$

$$\begin{aligned} b_{41}(x) &= b_{42}(x) = b_{43}(x) = b_{51}(x) = b_{52}(x) = b_{53}(x) = b_{61}(x) \\ &= b_{62}(x) = b_{63}(x) = 0 \end{aligned}$$

$$c_1 = C_{l_{\alpha_{MR}}} N_b R_{MR}^3 c_{MR} \Omega_{MR}^2 \rho$$

$$c_2 = C_{l_{\alpha_{MR}}} N_b R_{MR}^2 c_{MR} \Omega_{MR} \rho$$

Attitude Loop State Dependent Matrix Coefficients

$$b_{11}(x) = 1, b_{12}(x) = \sin(\phi) \tan(\theta), b_{13}(x) = \cos(\phi) \tan(\theta)$$

$$b_{32}(x) = \sin(\phi) / \cos(\theta), b_{33}(x) = \cos(\phi) / \cos(\theta)$$

$$\begin{aligned} b_{21}(x) &= b_{31}(x) = b_{41}(x) = b_{42}(x) = b_{43}(x) = b_{51}(x) = b_{52}(x) \\ &= b_{53}(x) = b_{61}(x) = b_{62}(x) = b_{63}(x) = 0 \end{aligned}$$

$$A(x) = \begin{bmatrix} 0_{3 \times 3} & 0_{3 \times 3} \\ I_{3 \times 3} & 0_{3 \times 3} \end{bmatrix}$$

Speed Loop State Dependent Matrix Coefficients

$$a_{11}(x_{SPD}) = -\frac{c_2}{m} \left\{ \left(\frac{1}{8} + \frac{3e}{16} \right) \beta_{1c}^2 + \left(\frac{e}{16} \right) \beta_{1s}^2 \right\} - \frac{c_3}{4m} - \frac{c_4}{2m} |U_b|$$

$$a_{12}(x_{SPD}) = r + z \frac{c_2}{8m} \beta_{1s} \beta_{1c}$$

$$a_{21}(x_{SPD}) = \frac{c_2}{8m} \left[(1+e) \beta_{1s} \beta_{1c} - \left(\frac{3\gamma_{MR}}{4} \right) \beta_0 \right] - r$$

$$a_{22}(x_{SPD}) = - \left(\frac{c_2}{8m} \beta_{1s}^2 + \frac{c_3}{4m} + \frac{c_8}{2m} |V_b| \right)$$

$$\begin{aligned} a_{13}(x_{SPD}) &= a_{14}(x_{SPD}) = a_{23}(x_{SPD}) = a_{24}(x_{SPD}) \\ &= a_{32}(x_{SPD}) = a_{33}(x_{SPD}) = a_{34}(x_{SPD}) \\ &= a_{41}(x_{SPD}) = a_{43}(x_{SPD}) = a_{44}(x_{SPD}) = 0 \end{aligned}$$

$$a_{31}(x_{SPD}) = a_{42}(x_{SPD}) = 1$$

$$b_{12} = -gL_1, b_{21} = g \cos(\theta)L_2$$

$$b_{11}(x) = b_{22}(x) = b_{31}(x) = b_{32}(x) = b_{41}(x) = b_{42}(x) = 0$$

$$L_1 = \text{sinc}(\theta), L_2 = \text{sinc}(\phi)$$

$$\begin{aligned} c_2 &= C_{l_{\alpha_{MR}}} N_b R_{MR}^2 c_{MR} \Omega_{MR} \rho, c_3 = C_d N_b R_{MR}^2 c_{MR} \Omega_{MR} \rho \\ c_4 &= A_x D_{x_{fus}} \rho, c_8 = A_y D_{y_{fus}} \rho \end{aligned}$$

Vertical Speed Loop State Dependent Matrix Coefficients

$$a_{11}(x_{VS}) = -\frac{1}{m} \left[\left(\frac{c_9}{2} \right) |W_b| \right], a_{21}(x_{VS}) = 1$$

$$a_{12}(x_{VS}) = a_{22}(x_{VS}) = 0$$

$$b_1(x) = -\frac{c_1}{m} \left(\frac{4}{25} + \frac{1}{2}e + \frac{1}{2}e^2 - \frac{29}{25}e^3 \right) - \frac{c_7}{4m} U_b^2, b_2(x) = 0$$

$$c_1 = C_{l_{\alpha_{MR}}} N_b R^3 c_{MR} \Omega_{MR}^2 \rho, c_7 = C_{l_{\alpha_{MR}}} N_b R_{MR} c_{MR} \rho$$

$$c_9 = A_z D_{z_{fus}} \rho$$